

Probabilistic Constrained Optimization on Flow Networks

Michael Schuster

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Friedrich-Alexander Universität Erlangen-Nürnberg (FAU),
Department of Mathematics

Motivation

Probabilistic Constraints

Consider the optimization problem

$$\begin{aligned} \min_{x \in \mathcal{X}} \quad & f(x) \\ \text{s.t.} \quad & \mathbb{P}(g(x, \xi) \leq 0) \geq \alpha \end{aligned}$$

with objective function f , constraint g , decision vector x , random variable ξ (with probability distribution and density function) and probability level α .

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How can we evaluate the probability?

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with objective function f , constraint g , decision vector x , random variable ξ (with probability distribution and density function) and probability level α .

We have

$$\mathbb{P}(g(x, \xi) \leq 0) = \int_{M(x)} \varrho_{\xi}(z) dz,$$

with

$$M(x) = \{ \omega \in \Omega \mid g(x, \xi(\omega)) \leq 0 \}.$$

Motivation

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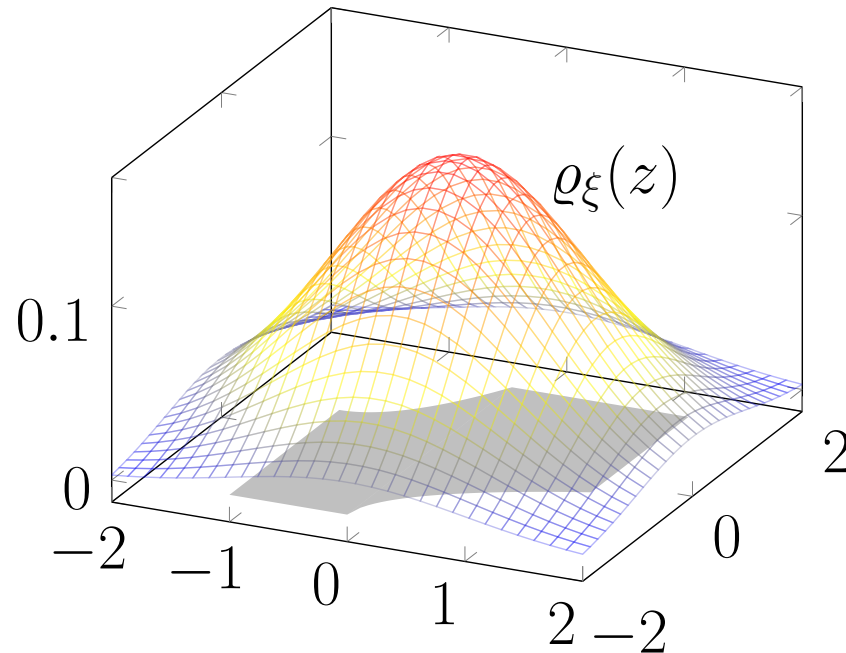
$$\mathbb{P}(g(x, \xi) \leq 0) = \int_{M(x)} \varrho_{\xi}(z) dz,$$

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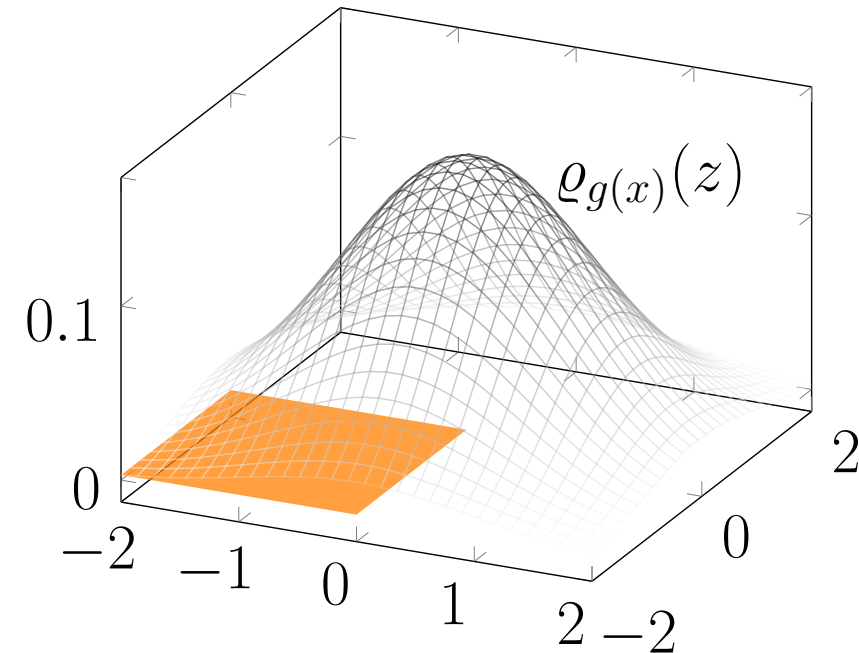
Is there a „better“ way to compute this probability?

Idea: Forward transformation of M along g



(a) Well-known distribution (colored), unknown set of feasible loads (grey)

$\xrightarrow{g(x, \cdot)}$



(b) Unknown distribution (grey), well-known set of feasible pressures (orange)

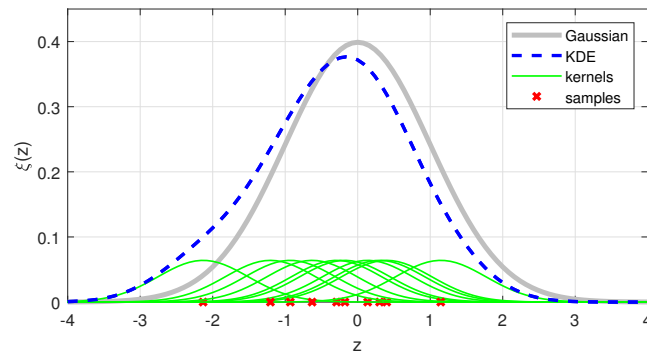
Kernel Density Estimation

Definition: Kernel Density Estimator

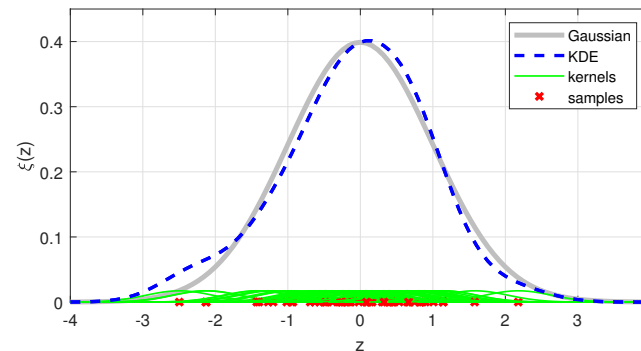
Let $\mathcal{Y} = \{y_1, \dots, y_{N_{\text{KDE}}}\} \subseteq \mathbb{R}^n$ be i.i.d. samples of the random variable Y , which has an absolutely continuous distribution function with probability density function ϱ . Let K be a n -dimensional kernel function.

Then the kernel density estimator $\varrho_{N_{\text{KDE}}}$ corresponding to the bandwidth matrix $H \in \mathbb{R}^{n \times n}$ is defined as

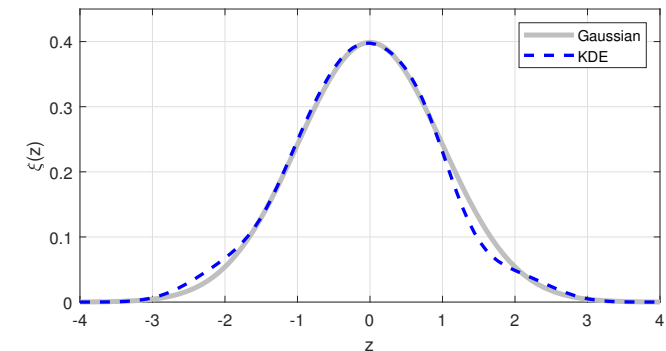
$$\varrho_{N_{\text{KDE}}}(z) = \frac{1}{N_{\text{KDE}} \det(H)^{\frac{1}{2}}} \sum_{i=1}^{N_{\text{KDE}}} K\left(H^{-\frac{1}{2}}(z - y_i)\right).$$



(a) KDE with 10 samples



(b) KDE with 50 samples



(c) KDE with 100 samples

Evaluating Probabilities

Application of the KDE

- Let $\mathcal{S} = \{s_1, \dots, s_{N_{\text{KDE}}}\}$ be independent and identically distributed samples of the random variable ξ .
- Let $\mathcal{G}_{\mathcal{S}}(x) = \{g(x, s_1), \dots, g(x, s_{N_{\text{KDE}}})\}$ be the corresponding sample of the constraint g (also independent and identically distributed) for $x \in \mathcal{X}$.

Multivariate Gaussian kernel

$$K(z) = \frac{1}{(2\pi)^{\frac{n}{2}}} \exp\left(-\frac{1}{2} \|z\|^2\right)$$

Diagonal bandwidth matrix

$$H_{i,i} = h^2 (\Sigma_{N_{\text{KDE}}})_{i,i}$$

$$h = \left(\frac{4}{(n+2)N_{\text{KDE}}}\right)^{\frac{1}{n+4}}$$

$$\varrho_{N_{\text{KDE}}}(z) = \frac{1}{N_{\text{KDE}} \det(H)^{\frac{1}{2}}} \sum_{i=1}^{N_{\text{KDE}}} K\left(H^{-\frac{1}{2}}(z - g(x, s_i))\right)$$

M. Schuster (2021): *Nodal Control and Probabilistic Constrained Optimization using the Example of Gas Networks*. Dissertation, FAU Erlangen-Nürnberg, Germany, 2021.

<https://opus4.kobv.de/opus4-trr154/frontdoor/index/index/docId/410>

M. Schuster, E. Strauch, M. Gugat, J. Lang (2022): *Probabilistic Constrained Optimization on Flow Networks*. Optim. Eng. 23, pp. 1–50.

Application of the KDE

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$$h = \left(\frac{4}{(n+2)N_{\text{KDE}}}\right)^{\frac{1}{n+4}}$$

$$\begin{aligned} \varrho_{N_{\text{KDE}}}(z) &= \frac{1}{N_{\text{KDE}} \det(H)^{\frac{1}{2}}} \sum_{i=1}^{N_{\text{KDE}}} K\left(H^{-\frac{1}{2}}(z - g(x, s_i))\right) \\ &= \frac{1}{N_{\text{KDE}} \det(H)^{\frac{1}{2}}} \sum_{i=1}^{N_{\text{KDE}}} \prod_{j=1}^n \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} \left(\frac{z_j - g_j(x, s_i)}{\sqrt{H_{j,j}}}\right)^2\right) \end{aligned}$$

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$$\begin{aligned}\mathbb{P}_{N_{\text{KDE}}}(g(x, \xi) \leq 0) &= \int_{(-\infty, 0]^n} \varrho_{N_{\text{KDE}}}(z) dz \\ &= \int_{(-\infty, 0]^n} \frac{1}{N_{\text{KDE}} \det(H)^{\frac{1}{2}}} \sum_{i=1}^{N_{\text{KDE}}} \prod_{j=1}^n \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} \left(\frac{z_j - g_j(x, s_i)}{\sqrt{H_{j,j}}}\right)^2\right) dz \\ &= \frac{1}{N_{\text{KDE}} \det(H)^{\frac{1}{2}}} \sum_{i=1}^{N_{\text{KDE}}} \prod_{j=1}^n \int_{-\infty}^0 \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} \left(\frac{z_j - g_j(x, s_i)}{\sqrt{H_{j,j}}}\right)^2\right) dz_j\end{aligned}$$

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Gauss error function: $\text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x \exp(-t^2) dt$

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probability via KDE

$$\mathbb{P}_{N_{\text{KDE}}}(g(x, \xi) \leq 0) = \frac{1}{N_{\text{KDE}} 2^n} \sum_{i=1}^{N_{\text{KDE}}} \prod_{j=1}^n \left[1 - \text{erf}\left(\frac{g_j(x, s_i)}{\sqrt{2} H_{j,j}}\right) \right]$$

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Application of the KDE

We consider the following probabilistic constrained optimization problem and its approximation:

$$(P_{\infty}) \quad \begin{cases} \min_{x \in \mathcal{X}} & f(x) \\ \text{s.t.} & \mathbb{P}(g(x, \xi) \leq 0) \geq \alpha \end{cases}$$

$$(P_{N_{\text{KDE}}}) \quad \begin{cases} \min_{x \in \mathcal{X}} & f(x) \\ \text{s.t.} & \mathbb{P}_{N_{\text{KDE}}}(g(x, \xi) \leq 0) \geq \alpha \end{cases}$$

We assume, that both problems have at least one solution.

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Theorem 1

Let x^* be a solution of (P_∞) with $\mathbb{P}(g(x^*, \xi) \leq 0) > \alpha$. Then there exists N_{KDE}^* sufficiently large, s.t. x^* is also a solution of $(P_{N_{\text{KDE}}})$ for all $N_{\text{KDE}} > N^*$ \mathbb{P} -almost surely.

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Theorem 2

If the KDE \mathbb{P} -almost surely uniformly converges for every $x \in \mathcal{X}$, and if $(x_{N_{\text{KDE}}}^*)_{N_{\text{KDE}} \geq 1}$ is a convergent sequence of solutions of $(P_{N_{\text{KDE}}})$, then its limit x^* is \mathbb{P} -almost surely a solution of (P_∞) .

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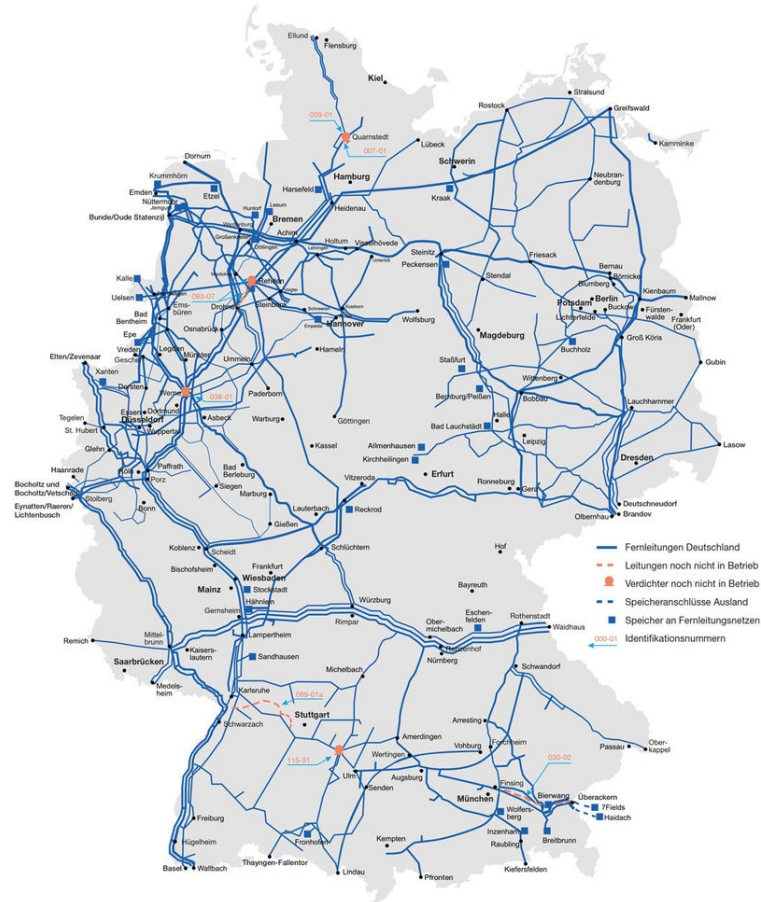
If the KDE \mathbb{P} -almost surely uniformly converges for every $x \in \mathcal{X}$, and if $(x_{N_{\text{KDE}}}^*)_{N_{\text{KDE}} \geq 1}$ is a convergent sequence of solutions of $(P_{N_{\text{KDE}}})$, then its limit x^* is \mathbb{P} -almost surely a solution of (P_∞) .

Theorem 3

If x^* is a unique solution of (P_∞) and if $f(x) - f(x^*) < \varepsilon$ only in an area around x^* , then there \mathbb{P} -almost surely exists a convergent sequence of solutions of $(P_{N_{\text{KDE}}})$.

Application to Gas Flow in Pipelines

Motivation



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Application to Gas Flow in Pipelines

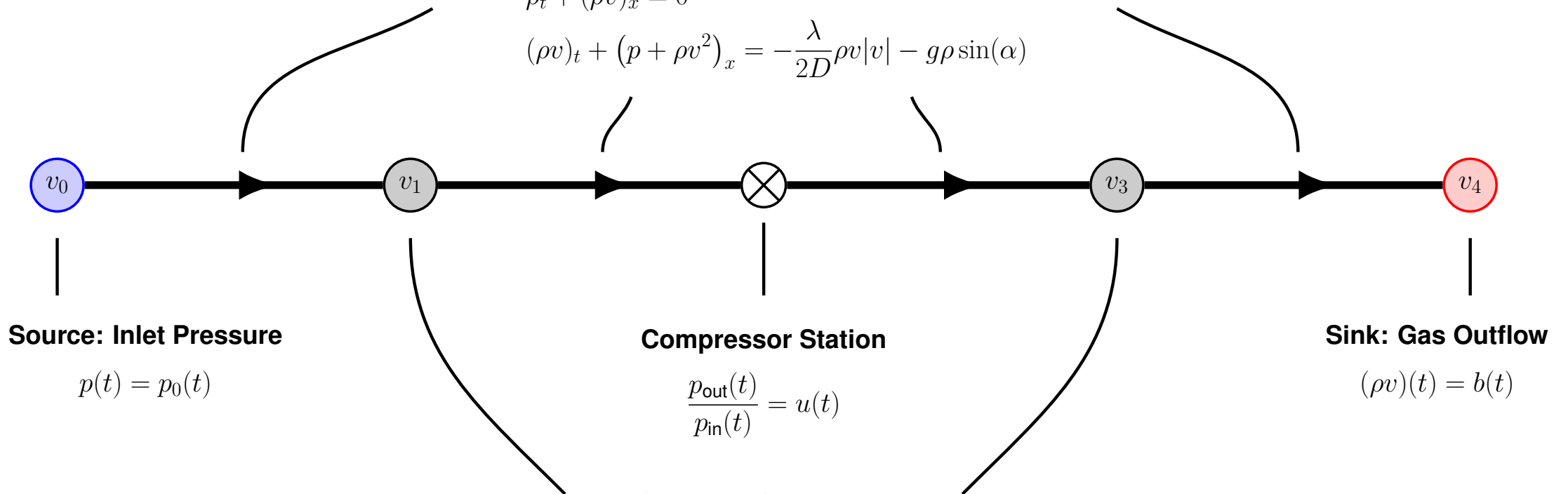
Gas Network Modelling

p	gas pressure	v	gas velocity	g	gravitational constant
ρ	gas density	λ/D	pipe friction	α	pipe slope

Isothermal Euler Equations

$$\rho_t + (\rho v)_x = 0$$

$$(\rho v)_t + (p + \rho v^2)_x = -\frac{\lambda}{2D} \rho v |v| - g \rho \sin(\alpha)$$



Source: Inlet Pressure

$$p(t) = p_0(t)$$

Compressor Station

$$\frac{p_{\text{out}}(t)}{p_{\text{in}}(t)} = u(t)$$

Sink: Gas Outflow

$$(\rho v)(t) = b(t)$$

Coupling Conditions

Conservation of Mass: $\sum (\rho v)_{\text{in}}(t) = \sum (\rho v)_{\text{out}}(t),$ Continuity in Pressure: $p_{\text{in}} = p_{\text{out}}$

Application to Gas Flow in Pipelines

The Isothermal Euler Equations

The isothermal Euler equations for ideal gases:

(ISO)

$$\begin{aligned} \rho_t + q_x &= 0, \\ q_t + \left(c^2 p + \frac{q^2}{\rho} \right)_x &= -\frac{\lambda^F}{2D} \frac{q|q|}{\rho}. \end{aligned}$$

Inlet density & Gas outflow

$$\begin{aligned} \rho(t, 0) &= \rho_0(t), \\ q(t, L) &= b(t). \end{aligned}$$

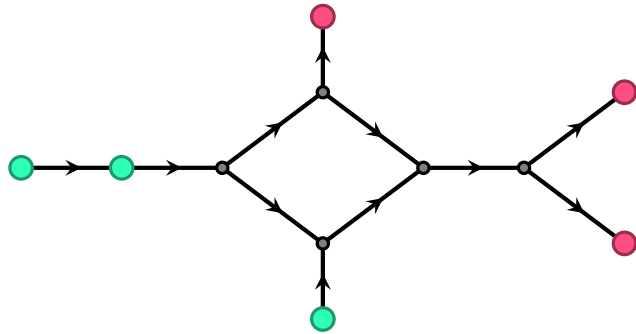
Initial condition

$$\begin{aligned} \rho(0, x) &= \rho_{ini}(x), \\ q(0, x) &= q_{ini}(x). \end{aligned}$$

Gugat and Ulbrich (2018): *Lipschitz solutions of initial boundary value problems for balance laws.* Math. Models Methods Appl. Sci., 28(5): 921–951

Application to Gas Flow in Pipelines

Stationary Gas Networks



p_0	p^{\min}	outflow ξ	covariance	α
$\begin{pmatrix} 60 \\ 58 \\ 60 \end{pmatrix}$	$\begin{pmatrix} 40 \\ 40 \\ 40 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 15 \\ 18 \end{pmatrix}$	$\begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$	75%

Deterministic optimization

$$\begin{aligned} \min_{p_{\text{det}}^{\max}} \quad & \sum p_{\text{det}}^{\max}, \\ \text{s.t.} \quad & \text{Gas Network Model,} \\ & p_i \in [p_i^{\min}, p_{\text{det},i}^{\max}] \end{aligned} \quad \Rightarrow \quad p_{\text{det}}^{\max} = \begin{pmatrix} 46.10 \\ 52.04 \\ 51.08 \end{pmatrix}$$

Probabilistic optimization

$$\begin{aligned} \min_{p_{\text{prob}}^{\max}} \quad & \sum p_{\text{prob}}^{\max}, \\ \text{s.t.} \quad & \text{Gas Network Model,} \\ & \mathbb{P} (p_i \in [p_i^{\min}, p_{\text{prob},i}^{\max}]) \geq 0.75. \end{aligned} \quad \Rightarrow \quad p_{\text{prob}}^{\max} = \begin{pmatrix} 47.52 \\ 53.34 \\ 52.45 \end{pmatrix}$$

How good is the optimal deterministic solution in the probabilistic setting?

$$\mathbb{P} (b \in M(p_{\text{det}}^{\max})) \approx 35.4\%$$

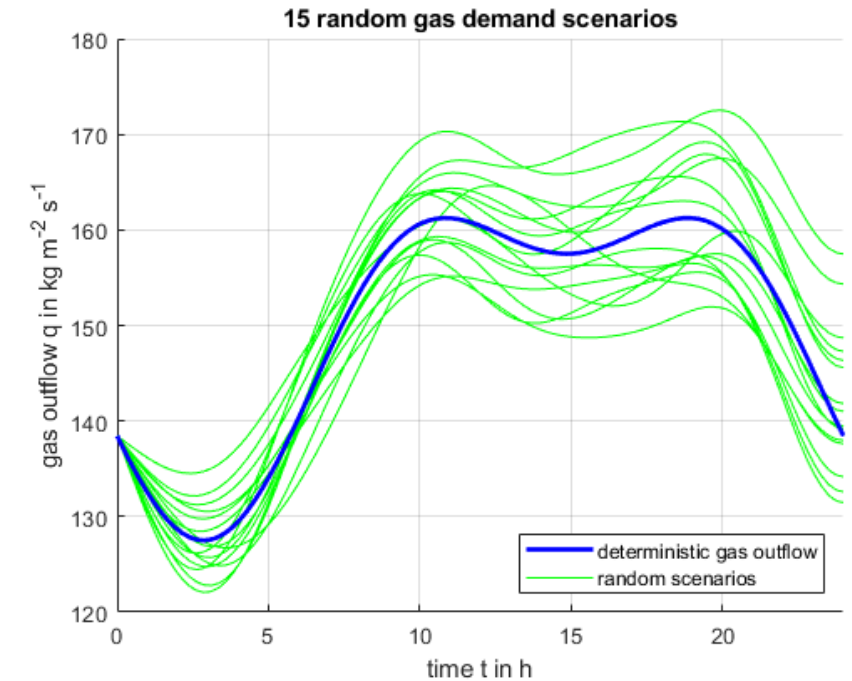
Random Boundary Functions

- Write a function f as Fourier series

$$f(t) = \sum_{m=0}^{\infty} a_m^0(f) \psi_m(t)$$

- For random variables $\xi_m \sim \mathcal{N}(1, \sigma)$ define

$$f^\omega(t) = \sum_{m=0}^{\infty} \xi_m(\omega) a_m^0(f) \psi_m(t)$$



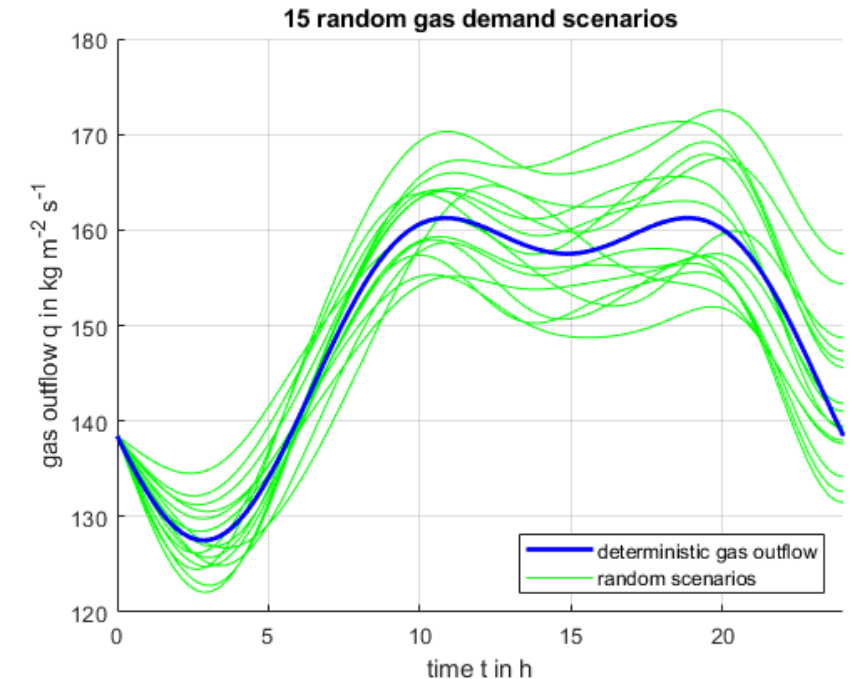
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Time dependent probabilistic constraint

$$\mathbb{P}(f^\omega \in M(t) \quad \forall t \in [0, T]) \geq \alpha$$

„We want to guarantee that a percentage α of all possible random scenarios is feasible in every point in time $t \in [0, T]$.“

Application to Gas Flow in Pipelines

Dynamic Probabilistic Constraints

- Let $\mathcal{B} = \{ b^{S,1}(t), \dots, b^{S,N_{\text{KDE}}}(t) \}$ be independent and identically distributed random boundary functions
- There exists a solution $\rho \in C(0, T; L^2(0, L))$, i.e. the densities are continuous in time
- Let $\mathcal{P}_{\mathcal{B}} = \{ \rho(t; b^{S,1}), \dots, \rho(t; b^{S,N_{\text{KDE}}}) \}$ be the corresponding densities at the end of the pipe

$$\mathbb{P} \left(\rho(t, L) \in [\rho^{\min}, \rho^{\max}] \quad \forall t \in [0, T] \right) = \mathbb{P} \left(\begin{array}{l} \min_{t \in [0, T]} \rho(t, L) \in [\rho^{\min}, \rho^{\max}] \\ \max_{t \in [0, T]} \rho(t, L) \in [\rho^{\min}, \rho^{\max}] \end{array} \right)$$

Application to Gas Flow in Pipelines

Dynamic Probabilistic Constraints

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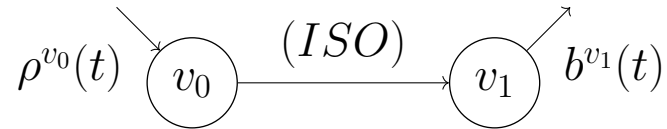
$$\mathbb{P} \left(\rho(t, L) \in [\rho^{\min}, \rho^{\max}] \quad \forall t \in [0, T] \right) = \mathbb{P} \left(\begin{array}{l} \min_{t \in [0, T]} \rho(t, L) \in [\rho^{\min}, \rho^{\max}] \\ \max_{t \in [0, T]} \rho(t, L) \in [\rho^{\min}, \rho^{\max}] \end{array} \right)$$

$$\Rightarrow \text{The sample } \left\{ \begin{array}{l} \left[\begin{array}{l} \underline{\rho}(b_1) := \min_{t \in [0, T]} \rho(t; b^{S,1}) \\ \bar{\rho}(b_1) := \max_{t \in [0, T]} \rho(t; b^{S,1}) \end{array} \right], \dots, \left[\begin{array}{l} \underline{\rho}(b_{N_{\text{KDE}}}) := \min_{t \in [0, T]} \rho(t; b^{S,N_{\text{KDE}}}) \\ \bar{\rho}(b_{N_{\text{KDE}}}) := \max_{t \in [0, T]} \rho(t; b^{S,N_{\text{KDE}}}) \end{array} \right] \end{array} \right\} \subseteq \mathbb{R}^{2n}$$

is a sample of random numbers and we can apply the KDE-approach as introduced before.

Application to Gas Flow in Pipelines

Dynamic Probabilistic Constraints



$\rho_0(t)$	ρ^{\min}	c	λ^F	D	L	T	α
46.75 kg/m ³	34 kg/m ³	343 m/s	0.1	0.5 m	30 km	24 h	90%

Deterministic Optimization

$$\min_{\rho_{\det}^{\max}} \rho_{\det}^{\max},$$

s.t. Isothermal Euler Equations,
 $\rho(t, L) \in [\rho^{\min}, \rho_{\det}^{\max}]$

$$\Rightarrow \rho_{\det}^{*,\max} = 42.15 \text{ kg/m}^3$$

Probabilistic Optimization

$$\min_{\rho_{\text{prob}}^{\max}} \rho_{\text{prob}}^{\max},$$

s.t. Isothermal Euler Equations

$$\mathbb{P} \left(\rho(t, L) \in [\rho^{\min}, \rho_{\text{prob}}^{\max}] \quad \forall t \in [0, T] \right) \geq 0.9.$$

$$\Rightarrow \rho_{\text{prob}}^{*,\max} = 42.49 \text{ kg/m}^3$$

How good is the optimal deterministic solution in the probabilistic setting?

$$\mathbb{P} \left(b(t) \in M(t; \rho_{\det}^{\max}) \quad \forall t \in [0, T] \right) \approx 50\%$$

Application to Gas Flow in Pipelines

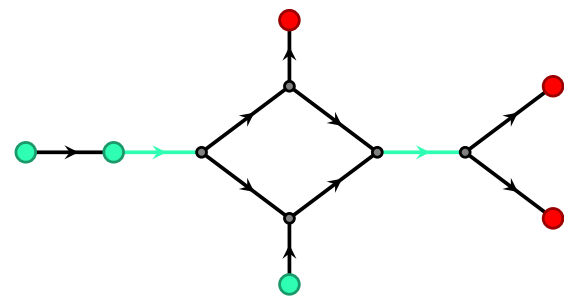
Probabilistic Robustness

Let bounds for the pressures $0 < p_{\min} < p_{\max}$ be given at every node. For $\varepsilon > 0$ consider the optimal control problem

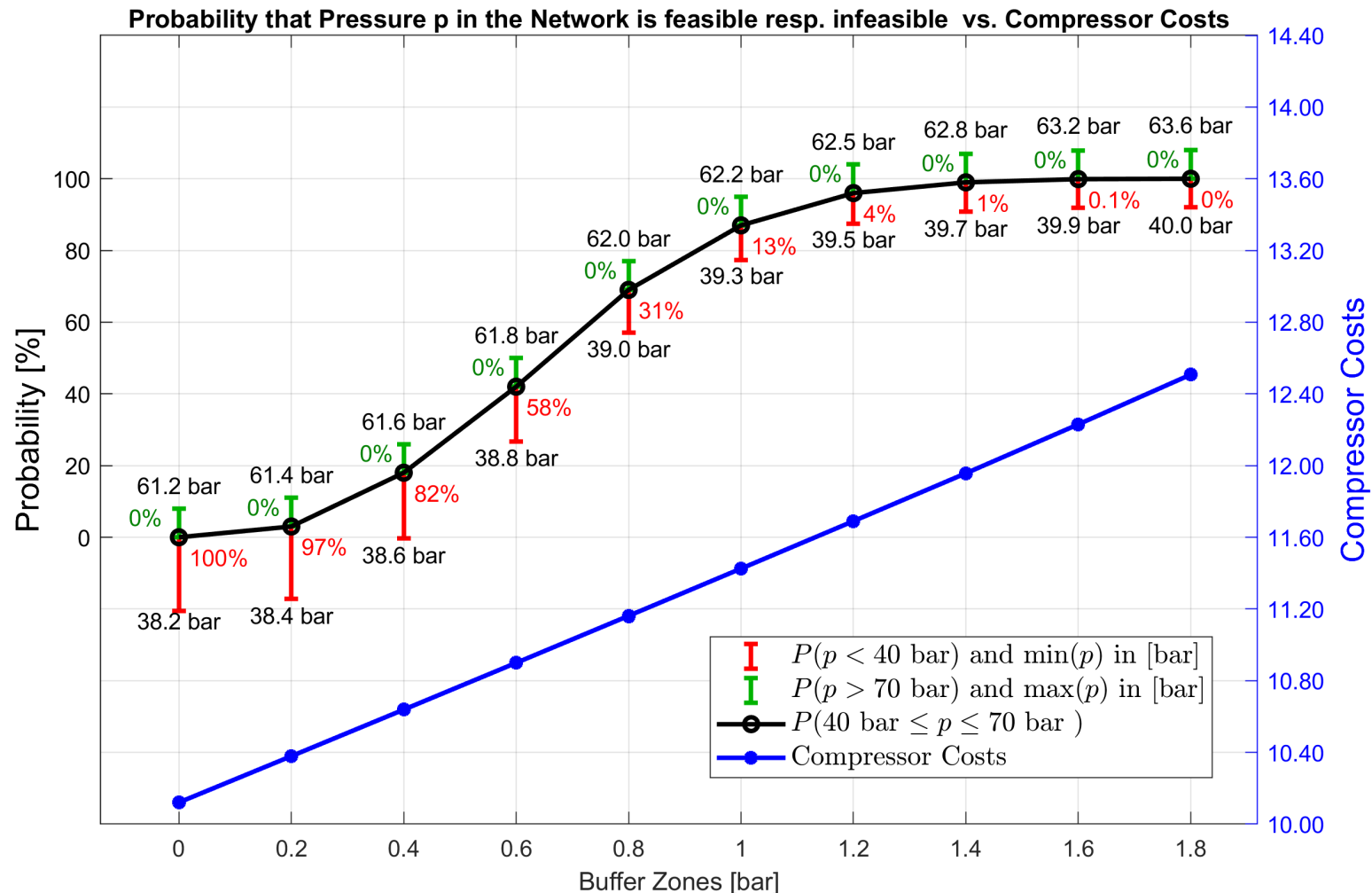
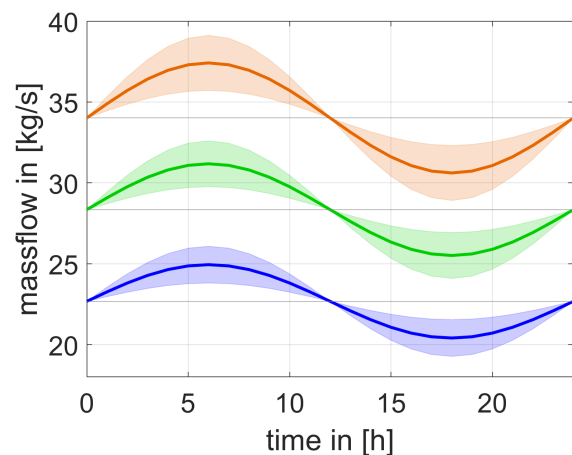
$$\begin{aligned} \min_{u(t)} \quad & f(u, q) \\ \text{s.t.} \quad & \rho_t + (\rho v)_x = 0 && \text{on every edge} \\ & (\rho v)_t + (p + \rho v^2)_x = -\frac{\lambda}{2D} \rho v |v| - g \rho \sin(\alpha) && \text{on every edge} \\ & p(t) = p_0(t) && \text{on every source node} \\ & (\rho v)(t) = b(t) && \text{on every sink node} \\ & \sum (\rho v)_{\text{in}}(t) = \sum (\rho v)_{\text{out}}(t) && \text{on every inner node} \\ & p_{\text{in}} = p_{\text{out}} && \text{on every inner node} \\ & \frac{p_{\text{out}}(t)}{p_{\text{in}}(t)} = u(t) && \text{for every compressor} \\ & p(t) \in [p_{\min} + \varepsilon, p_{\max} - \varepsilon] \quad \forall t \in [0, T] && \text{on every node} \end{aligned} \quad \left. \begin{array}{l} \text{Gas Network Model} \\ \\ \text{State Constraint} \end{array} \right\}$$

Application to Gas Flow in Pipelines

Probabilistic Robustness



● source ● junction → compr. station
● sink — pipe



Schuster, Wilka, Strauch, Lang, Gugat (2025): Probabilistic Robustness for Compressor Controls in Transient Pipeline Networks. Preprint to be submitted soon.

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